



# Crime Investigation With Mobile Sensor Data Using Gaussian SVM And KNN Classification

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## Abstract

Nowadays, mobile phones are common devices which can be used for the various useful purposes. This can include capturing the crime scene in real-time, reporting it and alerting the police officials as soon as possible. We present a novel approach for investigating the crime scenes using sensor data collected from mobile phones. The proposed method uses classification methods such as Gaussian SVM and KNN for identifying any crime event. We achieved an accuracy of 81% with KNN and 78% with Gaussian SVM. We can use this particular technique for future forensics and solve mysterious cases.

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## I. INTRODUCTION

In our surroundings, we see people visiting the malls, parks or any other public places. Criminal instances are common in such places. These criminal activities may include robbery, theft, extortion, assault, pickpocketing, abduction, murder and many more. The difference in body structure before and after the crime varies with time. If the body vitals such as rate of heartbeat, oxygen levels, body posture were monitored and recorded, it would prove to be useful for the police officials to get hold of the attacker. This would in turn ensure the safety of the common man. Real-time crime reporting and swift actions on these crimes is the major challenge in this world. With the increasing number of crimes, to ensure the safety of public, the police officials need to be aware of the crimes happening in real-time so that they can take actions accordingly.

The Internet of things is one such mechanism that can help the common man as well as the police officials in reducing the number of crimes. An efficient IoT system can be deployed in which the public can capture and report the crime in real-time. On the other hand, the police officials can be alerted through a mobile application and further timely actions can be taken. The main aim of an IoT system is

increased connectivity between humans and sensors. This also ensures decreased human deployment or intervention. The main goal of this proposed model is to develop a mobile application which increases the connectivity between the public and the police and helps to ensure the wellbeing of the common man. Figure 1 shows the proposed work flow diagram. We used multiple videos for the creation of normal and fight sequence datasets. This data is uploaded to the server for training. Machine learning is being used to analyze these datasets. Finally, the dataset collected in real-time is accurately classified into a normal and abnormal sequence.

## II. LITERATURE REVIEW

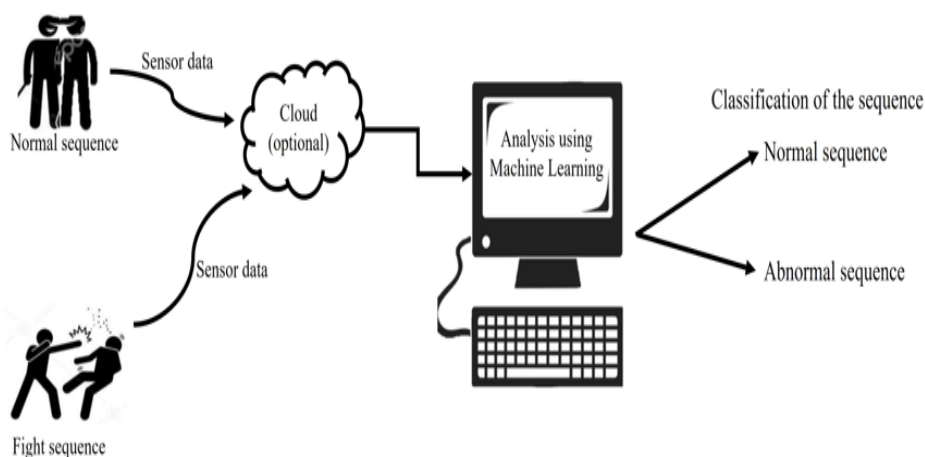
In 2019, Tundis and his teammates proposed a technique to detect and track criminals using IoT sensors. With the help of these IoT devices, communication was initiated amongst the officials and common man using a mobile application. The mobile application consists of various layers that perform different tasks. The first layer namely, IoT layer comprise of the devices that the user owns. The second layer is an intermediate layer called the edge layer which enables the collection of data and storage of data to the cloud. Lastly, the analysis layer



uses the data collected, performs analysis and presents a detailed result of the crime executed [1].

Lewis studied the effects of crimes on a community in 2012. The study included research on the the crime investigation and its mitigation techniques [2]. The study conducted by Lewis had three main goals, namely role of existing technology in prevention of crimes, development that can done in terms of technology for prevention of crimes and crime prevention techniques. The aim was to reduce the amount of crimes taking place in urban communities by making the common man aware of their surroundings.

This was done with the help of technology easily available to the common man. In 2013, Agangiba and Agangiba designed a device that was deployed in order to detect the crimes in the surroundings. The mobile device could also be used in reporting the crime. The user was allowed to upload any criminal evidences and contact the police officials through the mobile application. This information was transferred to a remote server using the Internet. The mobile application enabled the police to be aware of any criminal happenings in the surroundings as well as



**Fig. 1.** The flow of the proposed work. The datasets of normal and fight sequences are created by accessing multiple videos. The datasets are uploaded to the cloud. Analysis of these datasets is done with the help of machine learning. Lastly, the sensor data collected is classified into a normal and abnormal sequence with maximum accuracy.

take actions on those. If the remote server detected a regular offender, the police was informed accordingly [3].

A mobile application that monitored the streets was developed and deployed by Fernando. It was named as "Street Watch". This mobile application enabled its user to upload information of the crimes and alert the police officials for immediate action. Similarly, other users would also be aware of the crimes taking place in the close surroundings. It also stores the data of the past crimes. Thus incase a user enters a crime-prone area, the application notifies him or her about it [4].

In 2016, Jeon and Jeong, developed a system to prevent crime. Their system collected the database of crimes from publicly available sources and made the people aware. The proposed system deployed a system which included big data and Internet of Things.

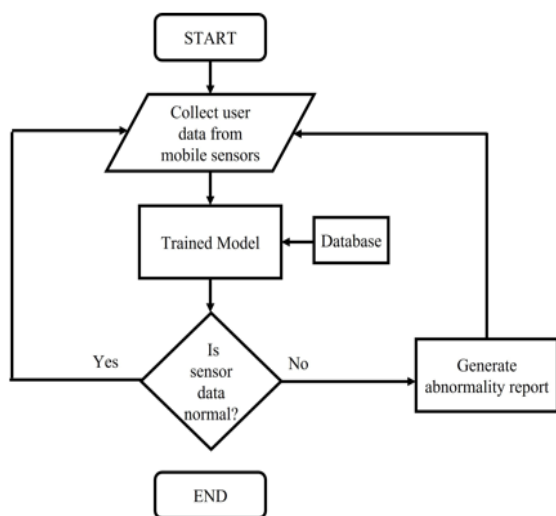
Collection of data was done using the a recording device. This recording was then compared to a reference to estimate and determine the severity of the crime. On the basis of the degree of crime, the user was notified through the phone or a wearable sensor device [5].

Recently, AIDahoul, Karim, Datta, Gupta, Agrawal, and Albunni (2021) designed a violence detection system using an LSTM based IoT node. The algorithm of Long Short Term Memory was executed on the Raspberry Pi. Videos of different types were captured and information was extracted. The training and validation datasets were RWF-2000 and RLVS-2000 respectively. The model displayed an accuracy of approximately 73%. On the basis of this model, the officials were alerted [6].

### III.METHODOLOGY

To collect mobile data, sensors need to be connected to the device and an object named MobileDEV needs to be created to store the data.

The sensor data was collected even when the device does not have a network connection using the sensor data log, which was stored locally. Periodic access to the camera and acquisition of the images was obtained at a set resolution, autofocus and flash mode. Other than images from the camera, acceleration, angular velocity, magnetic field, orientation and position were also logged.



**Fig. 2.** Proposed system flowchart. Data is collected using various mobile sensors, and the data is stored in an object called MobileDev.

KNN and Gaussian SVM machine learning models are used during model training for classification. Features such as principle component analysis are used on time series data. The results are saved in a database and sent to be analyzed further. Once trained the system goes through real-time sequence classification based on the trained model. If the data sequence is classified as "normal," then the sensors are instructed to continue collecting data. In the other case, i.e. the "abnormal" case, an abnormality report is generated.

Acceleration was measured in meter per second square whereas angular velocity was measured in radian per second, and magnetic field was measured in microtesla. Orientation is measured assuming elevation, XYZ coordinates and yaw roll, and pitch. Positions of the mobile recorded were latitude, longitude, speed, altitude, and course.

Latitude was measured in degrees with respect

to the equator where positive degrees indicate north and negative degrees indicate south. Longitude in degrees was with respect to meridian where positive indicates east and negative indicates west. Speed is measured in meters per second, altitude is measured in meters from sea level and course is measured in degrees with respect to true north.

To enable data transmission user needs to select "stream to cloud or log." Also, the user needs to select "send position data" in the background, "auto-upload". For the proof of concept, we collected the data manually and this data was classified as normal and as a fight scenario. To collect the data, the data logger app was installed into the user's mobile app.

Three similar fight sequences with a time interval of approximately 15 to 20 seconds were recorded. These fight sequences were recorded using the data logger app. The sampling rate was set to 300 milliseconds.

Parameters such as acceleration, angular velocity, magnetic field, orientation and position were extracted from the fight sequences. This technique was followed for all three sequences. A dataset containing all these findings was created for further processing. The normal and fight sequence dataset were compared.

In order to train a model which will be able to classify the normal and abnormal sequence, the k-nearest neighbors (KNN) and the Gaussian SVM algorithms were used. Here, a training dataset is generated through a mobile application. It is connected to various sensors which are deployed in various locations to record real-time data. The dataset is stored in an object called MobileDEV. The KNN algorithm is a classification technique that forms a group or cluster of similar looking data. The group or cluster is treated as a class. On the other hand, gaussian SVM is a classification technique that differentiates the dataset on the basis of features that are extracted from the data.

The figure 2 displays the flowchart of the proposed system. Data is collected with the help of various mobile sensors and an object named MobileDev is used to store the data. A machine learning model is trained using KNN and Gaussian SVM. The results are stored in a database and sent for further analysis. The system undergoes classification of sequence. In case the sequence is termed as "normal", the sensors are instructed to continue with



collecting data. However, in the reverse case, that is the "abnormal" case, an abnormality report is generated.

#### IV. RESULTS AND DISCUSSIONS

Figure 3 depicts various fight sequence data that were collected through the Matlab app. The latitude and longitude was recorded as 41.29 and 72.35 degrees respectively. The speed was 25 meters per second. The XYZ coordinates of the acceleration were recorded as 0.27, 0.23 and -10.19 meters per second square. Also, coordinates of angular velocity are -0.22, 0.07 and 0.06 radians per second respectively. The altitude was 200.1 meters while the horizontal accuracy was 9 meters.

```

mobiledev with properties:
    Connected: 1
    Available Cameras: {'back' 'front'}
    Logging: 1
    AccelerationSensorEnabled: 1
    AngularVelocitySensorEnabled: 1
    MagneticSensorEnabled: 1
    OrientationSensorEnabled: 1
    PositionSensorEnabled: 1

Current Sensor Values:
    Acceleration: [0.27 0.23 -10.19] (m/s^2)
    AngularVelocity: [-0.22 0.07 0.06] (rad/s)
    MagneticField: [3.56 1.56 -48.19] (microtesla)
    Orientation: [85.91 -27.1 0.35] (degrees)

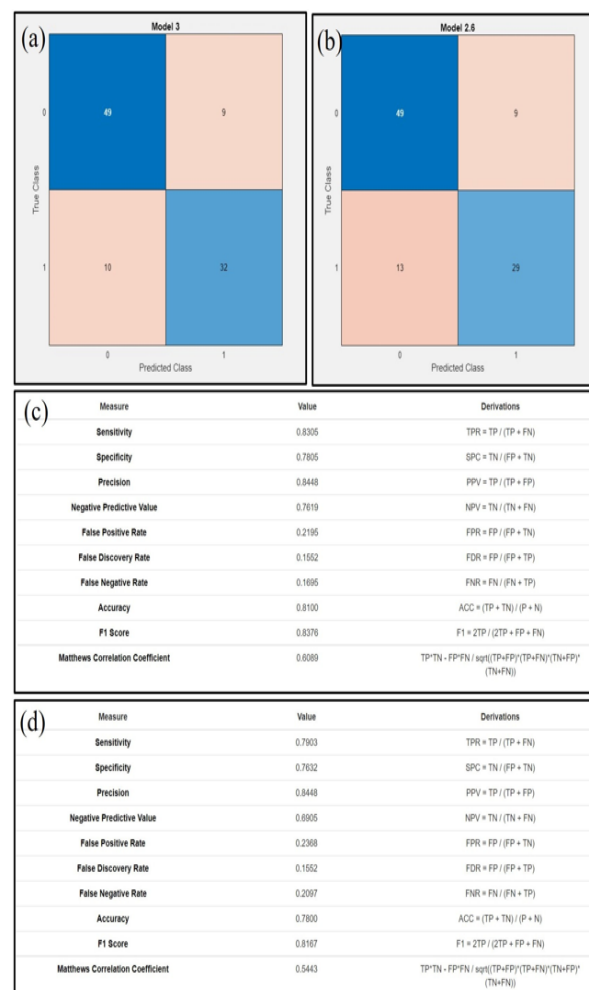
Position Data:
    Latitude: 41.29 (degrees)
    Longitude: -72.35 (degrees)
    Speed: 25 (m/s)
    Course: 83.6 (degrees)
    Altitude: 200.1 (m)
    HorizontalAccuracy: 9.0 (m)
    
```

**Fig. 3.** The sample of various data points that were determined for the fight sequence from different sensors. The figure 4 shows the various results obtained after the implementation of KNN and Gaussian SVM. The result parameters are measured in terms of sensitivity, specificity, precision, negative predictive value, false positive rate, false discovery rate, false negative rate, accuracy, F1 score and Matthews correlation coefficient as seen in figure 4c and 4d. With respect to KNN, the accuracy, F1 score and precision were recorded as 81, 83.76 and 84.48 respectively. On the other hand, the Gaussian SVM displayed an accuracy of 78, F1 score of 81.67 and a precision of 84.48. The sensitivity of KNN and Gaussian SVM was recorded as 0.8305 and 0.7903 respectively. The specificity of KNN was 0.7805 and that of Gaussian SVM was 0.7632. The negative predictive value, false positive rate, false discovery rate, false negative rate for KNN is 0.7619, 0.2195, 0.1552, 0.1695. The negative predictive value, false positive

rate, false discovery rate, false negative rate for Gaussian SVM is 0.6905, 0.2368, 0.1552, 0.2097. Lastly, the Matthews correlation coefficient for KNN and Gaussian SVM is 0.6089 and 0.5443 respectively.

#### V. CONCLUSIONS

Mobile phone is now very common devices that can be used for a variety of useful purposes. This can include capturing data the crime scene in real-time, reporting it, and notifying law enforcement officials as soon as possible. We present a novel method for investigating crime scenes that makes use of sensor data collected from mobile phones at the crime scene. For identifying any crime event, the proposed method employs classification methods such as Gaussian SVM and KNN. Our system is capable of segregating normal even with abnormal event, such as, assault. We achieved an accuracy of 81% with



**Fig. 4.** Results with two classification methods (a) Confusion matrix using KNN (b) Confusion matrix using Gaussian SVM. (c) Results obtained, after the KNN classification was implemented. (d) Results obtained,





after the Gaussian SVM classification was implemented. TP: True positive, FP: False positive, TN: True negative and FP: False positive were used for analysis purpose.

KNN and 78% with Gaussian SVM. This technique can be used in future forensics to solve mysterious cases.

## **APPENDIX A DECLERATIONS**

### **A. Authors' contributions:**

Conceptualization was done by Divya Shekhawat (DS). All the experiments/code executions were performed by Sukhada Aloni (SA) and DS. The formal analysis was performed by SA and DS. Manuscript writing-original draft preparation was done by SA. Review and editing were done by DS. Visualization work was carried out by SA and DS.

### **B. Funding information:**

No funding was involved in the present work.

### **C. Ethics approval:**

All authors consciously assure that the manuscript fulfills the following statements:

- 1) This material is the authors' own original work, which has not been previously published elsewhere.
- 2) The paper is not currently being considered for publication elsewhere.
- 3) The paper reflects the authors' own research and analysis in a truthful and complete manner.
- 4) The paper properly credits the meaningful contributions of co-authors and co-researchers.
- 5) The results are appropriately placed in the context of prior and existing research.

### **D. Conflicts of interest:**

Authors S. Aloni and D. Shekhawat declare that there has been no conflict of interest.

### **E. Consent to participate:**

This article does not contain any studies with animals performed by any of the authors. Informed consent was acquired from all human participants. All the necessary permissions were obtained from Institute Ethical committee and concerned authorities.

### **F. Consent for publication:**

Authors have taken all the necessary consents for publication from participants wherever required.

### **G. Code availability:**

Codes can be made available on reasonable request to the corresponding author.

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