



ENHANCING URBAN MOBILITY WITH DENSITY-BASED TRAFFIC LIGHT CONTROL SYSTEMS

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ABSTRACT

Due to deteriorating signal control systems and escalating traffic congestion, urban transportation is facing more and more difficulties. In order to improve urban mobility, this research presents a density-based traffic light management system that dynamically modifies traffic signals in response to real-time traffic density data. By monitoring vehicle flow at junctions with the use of sophisticated sensors and data analytics, the suggested system allows for adaptive signal timing, which improves traffic flow and lessens congestion.

The system measures traffic density and examines traffic patterns in real time by integrating vehicle identification technology like cameras and inductive loop sensors. The traffic lights use density-based algorithms to modify their timing in response to changing traffic circumstances. This allows them to prioritize green signals in areas with high traffic volumes and reduce delays for all users of the road.

In comparison to conventional fixed-timing traffic signals, preliminary findings show that the density-based control system greatly improves traffic flow and decreases wait times at crossings. Because of the adaptive nature of the system, peak and off-peak traffic may be better managed, resulting in less congestion and more seamless transitions between lanes.

By minimizing stop-and-go traffic, this strategy not only improves overall urban mobility but also helps to reduce car emissions and improve air quality. The research shows how density-based traffic signal control systems may revolutionize urban traffic management by offering contemporary cities a scalable and efficient alternative. In order to provide complete traffic control, future research will concentrate on improving the system's algorithms, extending its deployment, and combining it with other smart city technologies.

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I. INTRODUCTION

Globally, urban areas are seeing a rise in traffic congestion, leading to longer commutes, higher levels of automobile emissions, and a general decline in quality of life. Due to their reliance on set time schedules, traditional traffic light management systems often are unable to adjust to the dynamic nature of traffic flow, resulting in inefficiencies and congestion at junctions. Innovative strategies are required to improve urban mobility and traffic management in order to solve these issues.

A potential answer is provided by the density-based traffic light control system, which dynamically modifies signal timings in response to traffic density data collected in real time. Density-based systems employ sophisticated sensing technologies to detect vehicle counts and traffic flow at junctions, in contrast to traditional systems that follow preset schedules regardless of real traffic circumstances. With the use of this real-time data, the system is able to adjust traffic signal



cycles in accordance with the flow of traffic, which increases traffic efficiency and lessens congestion.

A variety of technologies are integrated into this system, such as data analytics platforms and vehicle detection sensors (such as cameras and inductive loops). Together, these parts gather and process traffic density data, which is subsequently used to modify how long green and red lights stay on. In order to provide longer green phases during periods of high traffic and shorter waiting times during periods of light traffic, it is important to make sure that traffic lights respond to real traffic demand.

By reducing delays and increasing fluidity of traffic, density-based traffic signal control systems have the potential to revolutionize urban traffic management. By reducing stop-and-go traffic circumstances, this adaptive method not only improves junction efficiency but also adds to environmental advantages including lower car emissions and better air quality.

Density-based traffic signal management systems are a crucial development in smart transportation solutions as cities expand and traffic patterns become more complicated. This paper addresses the difficulties of contemporary traffic management and emphasizes the function of such systems in improving urban mobility by examining their design, implementation, and possible effects.



Figure1. Working model

System Design and Implementation:

The following requirements are considered for the proposed density-based traffic light controller. Here's a system design for a density-based traffic light controller: Traffic Density Measurement:

- **Sensors:** Uses sensors such as ultrasonic or infrared sensors to measure the density of vehicles in each lane.
- **Sensor Placement:** Install the sensors at appropriate locations, such as the entrance or exit of each lane, to accurately detect the presence and movement of vehicles.
- **Data Processing:** Capture sensor data and process it to determine the traffic density in each lane. This can be achieved by counting the number of vehicles within a defined range or by analyzing the rate of vehicle detection.
- **Microcontroller:** Utilize an Arduino board or a similar microcontroller as the control unit of the traffic light controller.
- **Input Interface:** Connect the sensors to the microcontroller to receive the traffic density data.
- **Output Interface:** Connect the traffic light control circuitry to the microcontroller to control the traffic signals.
- **Thresholds:** Define thresholds for different traffic density levels. For example, low, medium, and high traffic density levels can be established based on the number of vehicles or the rate of vehicle detection.
- **Traffic Light Phases:** Designate different traffic light phases for each traffic density level. For instance, during low density, the green signal may last longer,

while during high density, the red signal may be extended.

- **Transition Conditions:** Establish conditions for transitioning between traffic light phases. For example, if the traffic density exceeds a certain threshold, switch from the current phase to the next phase.

Timing Intervals: Determine the duration of each traffic light phase based on the traffic density level. Longer green signals may be assigned to lanes with higher traffic density to facilitate smoother flow.

Synchronization: Synchronize the traffic light signals to ensure coordination among different lanes and optimize traffic flow. This can be achieved by using a master-slave configuration or a centralized control system.

Emergency Detection: Implement a mechanism to detect emergency vehicles, such as an emergency vehicle detection sensor or a manual override switch.

Priority Control: When an emergency vehicle is detected, give it priority by immediately switching the traffic lights to favor its movement. This can be done by interrupting the current traffic light phase and allocating a dedicated phase for the emergency vehicle to pass through.

Power Requirements: Provide a stable power supply for the microcontroller, sensors, and traffic lights. Use appropriate voltage regulators, batteries, or AC power sources.

Safety Considerations:

Implements safety features such as surge protection, short circuit protection, and adequate grounding to ensure reliable and safe operation of the system.

Display: Include an interface to display the current traffic light status, traffic density information, and any alerts or notifications.

Monitoring: Implement a monitoring system to collect data on traffic patterns, density, and signal timing for analysis and optimization purposes.

Remember to consider local traffic regulations and standards while designing the system and ensure compliance with any necessary certifications or approvals. This system design provides a high-level overview of a density-based traffic light controller.

Implementation details, such as the specific programming code and

hardware components, may vary based on your project requirements and the selected technology.

Block Diagram of Density based traffic light level controller

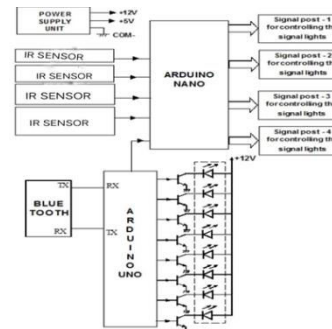


Figure.2 Block diagram of density based traffic light controller

Detail of Block Diagram

- A density-based traffic light controller is designed to regulate the flow of traffic at an intersection based on the density of vehicles present on each lane. The controller uses sensors to measure the vehicle density and adjusts the traffic light timings accordingly to optimize traffic flow and minimize congestion. While the specific block diagram can vary depending on the implementation, here are the key components typically involved.
- **Vehicle Density Sensors:** These sensors are placed at strategic locations near the intersection to detect the presence of vehicles on each lane. They can use various technologies such as infrared sensors, loop detectors, or camera systems to monitor the traffic density.
- **Microcontroller/Processor:** The microcontroller or processor acts as the brain of the traffic light controller. It receives input from the vehicle density sensors and makes decisions based on the programmed logic to control the traffic lights effectively. It executes the control algorithm and



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- **ControlAlgorithm:**Thecontrolalgorithmisresponsiblefordeterminingthe appropriate traffic light timings based on the input from the densitysensors. It analyzes the vehicle density data and calculates the optimaltimingpatternstoallocategreen,yellow,andred signalstoeach lane.
- **TrafficLightSignals:**Thetrafficlightsignalsindicatetheright-of-wayfor each lane of traffic. They typically consist of red, yellow, and greenlights. The signals are controlled by the microcontroller, which sendssignalstoactivatetheappropriate lightsbasedonthecontrolalgorithm'sdecisions.
- **Power Supply:** A power supply unit provides the necessary electricalpower to operate the entire traffic light controller system, including themicrocontroller,sensors,andtrafficlightsignals.
- **CommunicationInterface:**Insomeadvancedimplementations,thetraffic lightcontrollermayincludea communicationinterfacetocconnectwith a central traffic management system or other traffic controllers inthe area. This allows for coordination between multiple intersections tofurther optimizetrafficflow.
- **UserInterface(optional):**Auserinterfacemaybeincludedinthetrafficlight controller for configuration and monitoring purposes. It couldinclude buttons, switches, or a graphical display to adjust settings orviewssystemstatus.
- **Theblockdiagram**illustratestheflow ofinformationandsignalsbetweenthese components, highlightinghowtheyinteracttocontrolthetrafficlightsbasedonthemeasureddensityofvehicles.

II. ARDUINO UNO

TheArduinoUnoR3isadevelopmentboard basedontheATmega328.It has 14 digital input/output pins, 6 analog inputs, a 16 MHz ceramic resonator, a USBconnection, a power jack, an ICSP header, and a reset button. It contains everythingneeded to support the microcontroller; simply connect it to a computer with a USBcable or power it with an AC-to-DC adapter or battery to get started. The ArduinoUNO can be powered via a USB connection or with an external power supply. The power source is selected automatically. External (non-USB) power can come eitherfrom an AC-to-DC adapter (wall-wart) or a battery. The board can operate on anexternal supply of 6 to 20 volts. If supplied with less than 7V, however, the 5V pinmaysupplylessthanfivevoltsandtheboardmaybeunstable.Ifusingmorethan12V, thevoltage regulator mayoverheatand damage theboard.The recommendedrange is 7 to 12volts.

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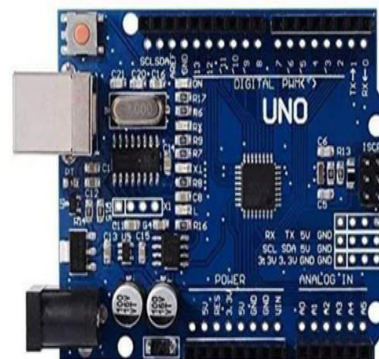


Figure 3 Arduino UNO

IR SENSORS

IR technology is used in a wider range of wireless applications which includes remote control and sensing. The infrared part in the electromagnetic spectrum can be separated into three main regions: near IR, mid-IR & far IR. The wavelengths of these three regions vary based on the application.

For the near IR region, the wavelength ranges from 700nm-1400nm, the wavelength of the mid-IR region ranges from 1400nm-3000nm & finally for the far



IR region, the wavelength ranges from 3000nm – 1 mm. The near IR region is used on fiber optic & IR sensors, the mid-IR region is used for heat sensing and the far IR region is used in thermal imaging. The range of frequency for IR is maximum as compared to microwave and minimum than visible light. This article discusses an overview of the IR sensor and its working. The photodiode used in this is very sensitive to the infrared light generated through an infrared LED. The resistance of photodiode & output voltage can be changed in proportion to the infrared light obtained. This is the fundamental IR sensor working principle. The type of incident that occurred is the direct otherwise indirect type where indirect type, the arrangement of an infrared LED can be done ahead of a photodiode without obstacle. In indirect type, both the diodes are arranged side by side through a solid object ahead of the sensor. The generated light from the infrared LED strikes the solid surface & returns back toward the photodiode.

The IR sensor module includes five essential parts like IR Tx, Rx, Operational amplifier, trimmer pot (variable resistor) & output light emitting diode (LED). The IR sensor module is representing in the figure below pin configuration of the IR sensor module is discussed below.

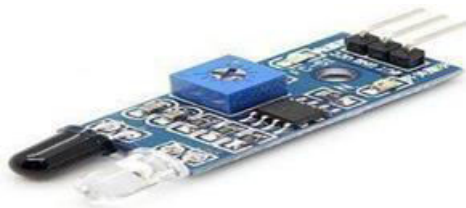


Fig:4 IR Sensor Module

LEDS

Light-emitting diode (LED) is a widely used standard source of light in electrical equipment. It has a wide range of applications ranging from your mobile phone to large advertising billboards. They mostly find applications in devices that show the time and display different types of data. A light-emitting diode (LED) is a semiconductor device that emits light when an electric current flows through it. When current passes through an LED, the electrons recombine with holes emitting light in the process. LEDs allow the current to flow in the forward direction and blocks

the current in the reverse direction.

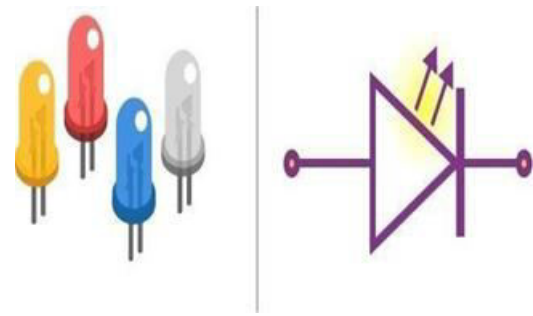


Figure 5 LEDs

BLUETOOTH HC-05

- It is used for many applications like wireless headset, game controllers, wireless mouse, wireless keyboard, and many more consumer applications.
- It has a range up to <100m which depends upon transmitter and receiver, atmosphere, urban conditions.
- It is IEEE 802.15.1 standardized protocol, through which one can build wireless Personal Area Network (PAN). It uses frequency-hopping spread spectrum (FHSS) radio technology to send data over air.

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It uses serial communication to communicate with devices. It communicates with microcontroller using serial port (USART).

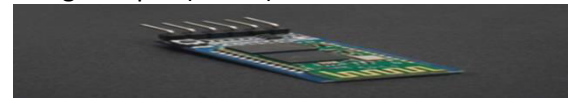


Figure 6: Bluetooth HC-05

**III. CIRCUIT DIAGRAM AND DESCRIPTION
 Circuit Diagram of Density Based Traffic Light Controller**

This project aims to improve the efficiency of traffic light system using Arduino based model. The traffic determination is done by IR sensors on each path. Using the details provided by the IR sensor we can guide the traffic signal to work efficiently with the traffic flow. The traffic density on each road determines the change of the timing of the signal. The road with the least traffic is assigned with the red signal and the one with the most traffic is assigned the green signal. In this project we imply the use of IR sensor.



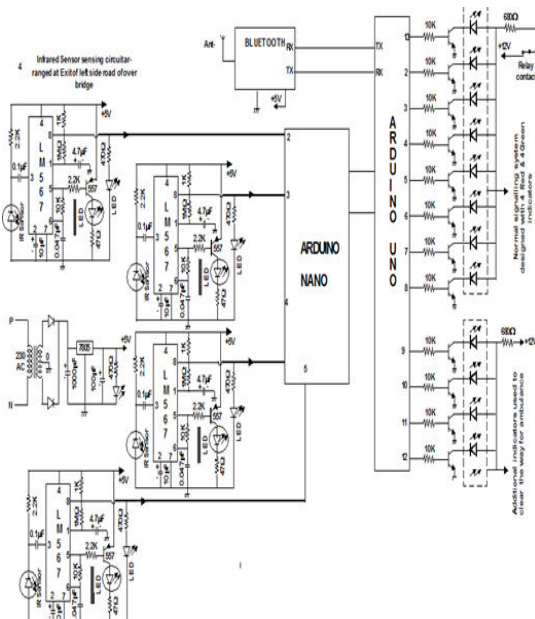


Figure 7. Circuit Diagram

Using Arduino Uno and HC-05 Bluetooth module, we can create a system for ambulance traffic clearance by implementing a wireless communication system between the ambulance and traffic signal control system. Here's a general outline of the process:

1. Hardware setup:

- Connect the HC-05 Bluetooth module to the Arduino Uno.
- Connect appropriate LEDs or signal lights to the Arduino Uno, representing the traffic signals.
- Ensure that the Arduino is powered and connected to a power source.

2. Coding the Arduino:

- Install the Arduino IDE and open a new sketch.
- Include the necessary libraries for Bluetooth communication.
- Set up the communication parameters for the HC-05 module (e.g., baudrate).
- Define the pin connections for the signal lights and configure them as outputs.
- Set up the Bluetooth connection and wait for incoming data.

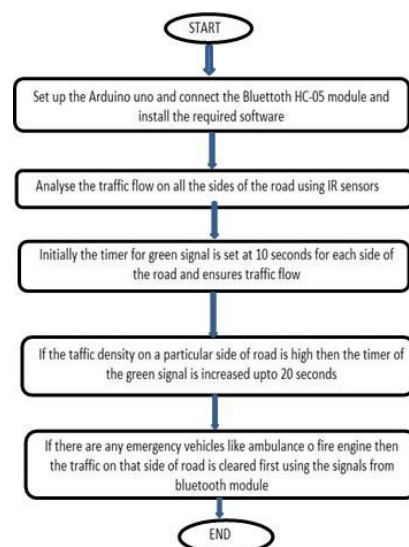
- When a signal is received via Bluetooth, interpret the data to determine the action required (e.g., ambulance approaching).

- Based on the received data, control the signal lights accordingly to clear the traffic for the ambulance.

3. Programming the Ambulance Device:

- Set up the Arduino microcontroller on the ambulance.
 - Connect the HC-05 Bluetooth module to the Arduino microcontroller.
 - Program the Arduino to send a specific signal when the ambulance is approaching.
4. Establish a Bluetooth connection with the traffic control system and send the signal indicating the ambulance's approach. Testing and Deployment:

- Upload the code to both the traffic control system and the ambulance device.
- Verify the hardware connections and ensure that the Bluetooth modules are properly paired.
- Test the system by sending signals from the ambulance to the traffic control system and observe if the traffic lights respond appropriately.
- Fine-tune the system as necessary and ensure its reliability.
- Once the system is working correctly, mount the hardware in the appropriate location and integrate it with the existing traffic signal infrastructure.



Advantages

- Efficient Traffic Flow: DBTLC systems can optimize traffic flow by dynamically adjusting signal timings based on the actual density of vehicles at an intersection. This helps to reduce



congestion and improve overall traffic efficiency.

- **Reduced Travel Time:** By responding to the real-time traffic conditions, DBTLC systems can minimize delays and queue lengths, leading to reduced travel times for vehicles.
- **Flexibility and Adaptability:** DBTLC systems are adaptable to changing traffic patterns and can adjust signal timings in response to varying traffic demands throughout the day. This flexibility allows for better coordination between intersections and improves the overall traffic network performance.
- **Improved Safety:** With optimized signal timings, DBTLC systems can enhance safety by minimizing the chances of collisions and reducing conflicts between vehicles and pedestrians.

4.2 Disadvantages

- **Accuracy:** The accuracy of the density-based traffic light controller depends on the quality of the sensors used to measure traffic density. If the sensors are not accurate or malfunction, the traffic flow may be affected.
- **Maintenance:** The use of sensors in the controller increases the complexity of the system and may require additional maintenance. The sensors may need to be calibrated periodically to ensure accurate measurements.
- **Complexity:** The implementation of a density-based traffic light controller using Arduino requires advanced programming skills and knowledge of electronic circuits. This complexity can make it difficult for beginners to work

Applications

- **Urban Traffic Management:** DBTLC systems are well-

suited for managing traffic in urban areas with high traffic volumes and complex intersection configurations. They can help optimize traffic flow and reduce congestion in busy city streets.

- **Intersection Control:** DBTLC systems can be implemented at intersections to regulate traffic signal timings based on real-time vehicle density. They can dynamically adjust the green, yellow, and red light durations to optimize the movement of vehicles through the intersection.
- **Smart City Initiatives:** DBTLC systems align with the concept of smart cities, where technology is utilized to improve urban infrastructure and enhance the quality of life for residents. Implementing these systems can contribute to better traffic management and more sustainable transportation networks.
- **Special Traffic Situations:** DBTLC systems can be particularly useful in managing traffic during special events, emergencies, or road works. They can adapt signal timings based on the changing traffic conditions to minimize disruptions and improve traffic flow.

IV. RESULT AND DISCUSSION

Density-based traffic light controller has been designed by using four IR sensors for four approaching road at a signal junction. These IR sensors count the number of vehicles in each direction and give this information to the Arduino. Depending on the information received, the controller takes the decision to give green signal to those particular direction vehicles whose density is much higher than other directions and allow them. And the rest of the signals will be in red for the duration of period defined in the controller. Likewise the



priority is given to that particular direction whose density is more and clears the traffic. Then the controller again checks the sensor inputs and will give signals appropriately depending on the density and for emergency vehicles like ambulance, fire engine etc. the communication system installed in the vehicles can clutch the traffic until they cross the signal post. The system is designed for junction/cross-roads, where often ambulance has to wait until the normal traffic is cleared. This is quite inconvenient for the patient who needs immediate treatment. There by this system is designed which can bypass the existing signaling system temporarily. There are traffic signals across the road to organize vehicles passage to avoid traffic congestion. Apart from this traffic maintenance, we should clear traffic for ambulances. But there is no such kind of systems at traffic signals. Traffic lights operated by police when it needs. Ambulances should have Bluetooth app in smart phone to give road priority to main system.



Figure 8. Result

V. CONCLUSION

A density-based traffic light controller has the potential to significantly improve traffic flow, reduce congestion, enhance efficiency, increase safety, and offer scalability and adaptability to varying traffic conditions. By dynamically adjusting signal timings based on real-time vehicle density, the controller can optimize traffic movements, minimize delays, and maximize the utilization of road capacity. However, the effectiveness of a density-based traffic light controller relies on the accuracy of sensing technology, reliability of communication infrastructure, and coordination with other traffic control measures. Further research and real-world trials are necessary to validate the perform

ance and feasibility of such controllers in different scenarios. Overall, implementing a density-based traffic light controller holds promise for creating smarter and more efficient transportation systems.

FUTURE SCOPE

An important development in urban traffic management is the use of density-based traffic signal control systems. These systems overcome the shortcomings of conventional fixed-timing traffic lights by dynamically modifying signal timings based on real-time traffic density data. An approach to traffic flow management at junctions that is more responsive and adaptable is made possible by the use of sophisticated sensors and data analytics.

According to the research, density-based traffic signal management systems may greatly increase traffic efficiency, lessen congestion, and cut down on motorist wait times. Through the optimization of green and red light phases based on real-time traffic circumstances, these technologies help to improve overall mobility in metropolitan areas and smoother traffic transitions. Reduced stop-and-go traffic also helps to cut down on automobile emissions, which benefits the environment and improves air quality.

The efficacy of density-based systems underscores their capacity to revolutionize urban traffic management by offering a scalable and proficient resolution to the obstacles presented by increasing traffic volumes and intricate patterns of congestion. To further improve traffic management and urban mobility, future research and development will concentrate on improving system algorithms, increasing deployment, and integrating these systems with other smart city technologies.

All things considered, density-based traffic light management systems provide a viable way to update traffic infrastructure and improve the sustainability and efficiency of urban transportation. Their importance in meeting the changing demands of modern cities and enhancing the quality of urban life

is highlighted by their capacity to adjust to traffic circumstances in real time.

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